

**LISTING OF CLAIMS**

This listing of claims will replace all prior version and listing of claims in the application:

1. (Currently amended) An image processing system comprising:  
  
an image input unit having a plurality of image input channels;  
  
a parallel image data processing unit that receives image data from the image input channels of the image input unit, divides the image data received from each of the input channels into a plurality of divided data, the number of divided data being less than a predetermined number of data that can be processed in parallel at a time, and processes in parallel the divided image data; and  
  
a sequential image data processing unit that sequentially processes the divided image data output from the image parallel data processing unit while switching the divided image data for the image input channels.
  
2. (Original) The image processing system according to claim 1, wherein the sequential image data processing unit carries out error diffusion processing between a target pixel and other pixels in pixel line of the target pixel.
  
3. (Original) The image processing system according to claim 2, further comprising:  
  
a storage unit that stores error data obtained by the error diffusion processing in compliance with the number of image data processed in parallel,  
  
wherein the sequential image data processing unit retrieves the error data stored for every input channel from the storage unit when performing the error diffusion processing.

4. (Original) The image processing system according to claim 1, further comprising:  
a blue noise processing unit that carries out blue noise processing;  
a blue noise data reading position designating unit that points a blue noise data reading position by the blue noise processing unit in parallel; and  
a reading position storage unit that stores the blue noise reading position for each image data to be processed in parallel,  
wherein the reading position storage unit stores the blue noise data reading position that corresponds to relevant image data at the time of blue-noise-processing the image data to be processed in parallel.

5. (Currently amended) An image forming system comprising:  
an image processing system including  
an image input unit having a plurality of image input channels;  
a parallel image data processing unit that receives image data from the image input channels of the image input unit, divides the image data received from each of the input channels into a plurality of divided data, the number of divided data being less than a predetermined number of data that can be processed in parallel at a time, and processes in parallel the divided image data; and  
a sequential image data processing unit that sequentially processes and outputs the divided image data output from the image parallel data processing unit while switching the divided image data for the image input channels; and  
an image forming unit that forms visible images on a recording medium using the image data output by the image processing system.

6. (Currently amended) An image processing method comprising:

receiving image data from a plurality of image input channels;  
dividing the image data received from each of the input channels into a plurality of divided data, the number of divided data being less than a predetermined number of data that can be processed in parallel at a time;  
processing in parallel the divided image data; and  
sequentially processing the divided image data processed at the processing while switching the divided image data for the image input channels.

7. (Original) The image processing method according to claim 6, wherein the sequentially processing includes carrying out error diffusion processing between a target pixel and other pixels in pixel line of the target pixel.

8. (Original) The image processing method according to claim 7, further comprising storing error data obtained by the error diffusion processing in compliance with the number of image data processed in parallel,

wherein the sequentially processing includes retrieving the error data stored for every input channel when performing the error diffusion processing.

9. (Original) The image processing method according to claim 6, further comprising:  
performing blue noise processing;  
designating a blue noise data reading position for performing the blue noise processing; and

storing the blue noise reading position, for each image data to be processed in parallel, that corresponds to relevant image data at the time of blue-noise-processing the image data to be processed in parallel.

10. (Currently amended) A computer-readable recording medium that stores a computer program that makes a computer execute:

receiving image data from a plurality of image input channels;

dividing the image data received from each of the input channels into a plurality of divided data, the number of divided data being less than a predetermined number of data that can be processed in parallel at a time;

processing in parallel the divided image data; and

sequentially processing the divided image data processed at the processing while switching the divided image data for the image input channels.

11. (Previously presented) The computer-readable recording medium that stores a computer program according to claim 10, wherein the sequentially processing includes carrying out error diffusion processing between a target pixel and other pixels in pixel line of the target pixel.

12. (Previously presented) The computer-readable recording medium that stores a computer program according to claim 11, further makes the computer execute storing error data obtained by the error diffusion processing in compliance with the number of image data processed in parallel,

wherein the sequentially processing includes retrieving the error data stored for every input channel when performing the error diffusion processing.

13. (Previously presented) The computer-readable recording medium that stores a computer program according to claim 10, further makes the computer execute:

performing blue noise processing;

designating a blue noise data reading position for performing the blue noise processing; and

storing the blue noise reading position, for each image data to be processed in parallel, that corresponds to relevant image data at the time of blue-noise-processing the image data to be processed in parallel.

14. (Canceled).